

The Case for Asynchronous Task Parallelism in Fortran

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Outline

- Overview of parallelism in Fortran
- Motivating use cases
- Prior art in OpenMP and OpenACC
- Code for a simple example
- **Possible Fortran implementations**

This talk is based on a blog post I wrote this summer: https://github.com/jeffhammond/blog/blob/main/Fortrans_Missing_Parallelism.md



Parallelism in Fortran 2018

! fine-grain parallelism	! (
! explicit	np
do concurrent (i=1:n)	n_]
Z(i) = X(i) + Y(i)	
end do	! >
! implicit	do
MATMUL	
TRANSPOSE	end
RESHAPE	syı

• • •

coarse-grain parallelism

- = num_images() local = n / np
- X, Y, Z are coarrays
- i=1,n local
 - Z(i) = X(i) + Y(i)
- d do
- nc all



- call my input(X,Y)
- do concurrent (i=1:n)
 - Z(i) = X(i) + Y(i)

call my output(Z)

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- call my input(X,Y)
- do concurrent (i=1:n)
 - Z(i) = X(i) + Y(i)

- call my_unrelated(A)

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- ! sequential on CPU
 call my_input(X,Y)
- ! parallel on GPU
 do concurrent (i=1:n)
 - Z(i) = X(i) + Y(i)

! sequential on CPU call my_unrelated(A)



! sequential on CPU
call my_input(X,Y)

! parallel on GPU w/ async do concurrent (i=1:n)

Z(i) = X(i) + Y(i)

! sequential on CPU w/ async call my unrelated(A)

Motivation for Asynchrony 2 (synthetic)



- call sub1(IN=A,OUT=B)
- call sub2(IN=C,OUT=D)
- call sub3(IN=E,OUT=F)
- call sub4(IN=B,IN=D,OUT=G)
- call sub5(IN=F,IN=G,OUT=H)
 - 5 steps require only 3 phases

Fortran compilers may be able to prove these procedures are independent but it is often impossible to prove that executing

Motivation for Asynchrony 2 (realistic)

Figure 3. The directed acyclic graph (DAG) representing data dependencies within one formulation of the CCSD method. The vertex labels are not important.



https://dl.acm.org/doi/10.1145/2425676.2425687 https://pubs.acs.org/doi/abs/10.1021/ct100584w





See https://github.com/ParRes/Kernels p2p* for details...

Motivation for Asynchrony 3



 $A_{i,j} = A_{i-1,j} + A_{i,j-1} - A_{i-1,j-1}$

This pattern appears in a range of applications:

- Deterministic neutron transport
- Dynamic programming for sequence alignment e.g. Smith-Waterman/PairHMM (bioinformatics)
- Linear algebra (e.g.NAS LU benchmark)



Parallel loop



Task dependency



Prior Art in OpenMP and OpenACC

Both of the popular directive-based models for parallel computing support asynchronous tasks in a range of operations.

OpenACC supports async and wait, with an implicit/default queue (stream) as well as explicit/numbered queues, and the ability to create dependency chains between operations, similar to CUDA streams.

OpenMP supports tasks with dependencies (and without). The syntax for dependencies is finer granularity - based on data references rather than queues - and the implementation may end up using a global queue as a result.

There are merits to both approaches, so the Fortran community will have to think about what form should be standardized.



These are examples of different things. Please don't try to compare them.

Prior Art in OpenMP and OpenACC

do i=1,n	!\$omp pa
<pre>!\$acc parallel loop async(i)</pre>	!\$omp ma
do j=1,m	do j=1,n
• • •	do i=1
enddo	!\$om
enddo	!\$om
do i=1,n	!\$om
!\$acc parallel loop async(i)	• • •
do j=1,m	!\$om
• • •	enddo
enddo	enddo
enddo	
ISacc wait	

- rallel
- ster
- , m
- np task
- mp& depend(in:grid(i-1)) &
- mp& depend(out:grid(j))
- np end task

e.g. https://github.com/ParRes/Kernels/blob/default/FORTRAN/p2p-tasks-openmp.F90



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Example

program main	
use numerot	
real :: A(100), B(100), C(100)	
real :: RA, RB, RC	
A = 1; B = 1; C = 1	
RA = yksi(A)	
RB = kaksi(B)	
RC = kolme(C)	
<pre>print*,RA+RB+RC</pre>	
end program main	

https://github.com/jeffhammond/blog/tree/main/CODE

```
module numerot
  contains
    pure real function yksi(X)
      real, intent(in) :: X(100)
      !real, intent(out) :: R
      yksi = norm2(X)
    end function yksi
    pure real function kaksi(X)
      real, intent(in) :: X(100)
      kaksi = 2*norm2(X)
    end function kaksi
    pure real function kolme(X)
      real, intent(in) :: X(100)
      kolme = 3*norm2(X)
    end function kolme
```

end module numerot



A coarray implementation?

program main	Coarray
use numerot	imago
real :: A(100) ! each image has one	inage-
real :: R	There i
A = 1	shared
<pre>if (num_images().ne.3) STOP</pre>	codes,
if (this_image().eq.1) R = yksi(A)	be requ
if (this_image().eq.2) R = kaksi(A)	
if (this_image().eq.3) R = kolme(A)	Une of
sync all	load-ba
call co_sum(R)	mechai
<pre>if (this_image().eq.1) print*,R</pre>	have to
end program main	always

ys are designed to support uted memory, hence are based on private data.

is limited opportunity for -memory optimizations in such as direct inter-image copies will uired.

The common motivations for ased models is dynamic alancing, but coarrays provide no nism for doing this, so users will o write their own, which they s do poorly.

A do concurrent implementation?

```
program main
  use numerot
  real :: A(100), B(100), C(100)
  real :: RA, RB, RC
  integer :: k
  A = 1; B = 1; C = 1
  do concurrent (k=1:3) ! reduction, someday
    if (k.eq.1) RA = yksi(A)
    if (k.eq.2) RB = kaksi(B)
    if (k.eq.3) RC = kolme(C)
  end do
  print*,RA+RB+RC
                                                 features.
 end program main
```

This implementation only supports independent tasks, and is likely completely useless when the implementation uses SIMD lanes or GPU threads for DO CONCURRENT (DC).

As with coarrays, the if (...eq...) is not scalable to more general examples. Do we want arrays of functions?

Both the coarray and DC are also *tedious and error prone*, which is a good justification for adding new language



do i=1,n	The block
task block async(i)	Dropondin
do j=1,m	is also a ta
• • •	asynchron
enddo	
end task block	
enddo	
task sync all	Important Is every in a tasl

- - state?

mechanism is used for scoping.

ig task implies this block scope ask, which can execute ously until synchronized.

questions: thing (e.g. I/O) allowed to be k?

How do tasks interact with shared

do i=1,n	The block
<pre>task block async(i) type :: private do i=1 m</pre>	Prependin is also a ta
ao j=1,m 	lt is essen task-priva
enddo end task block	covered b
enddo	
task sync all	

mechanism is used for scoping.

ng task implies this block scope ask.

itial to be able to have te state, which is already by the block feature.



real :: x
do i=1,n
<pre>task block async(i) shared(x)</pre>
type :: private
do j=1,m
• • •
enddo
end task block
enddo
task sync all

We also want to be able to describe the intent of data outside of the task, so we could reuse locality specifiers from DO CONCURRENT.

Locality specifiers already match OpenMP syntax, and a related feature in Fortran, so they are likely to be intuitive to Fortran programmers.

Task reductions are supported by OpenMP now, but the concept is tricky.

Atomics would be nice but that's a big bag of worms.

```
real :: x
do i=1,n
  task call foo(i,x)
enddo
task wait
do i=1,n
  task call foo(i,x) async(mod(i,2))
enddo
task sync 0
• • •
task sync 1
```

Calling subroutines as tasks is useful, but they should be **pure** in order to have reasonable behavior.

The right syntax for this is not obvious, but we can solve that later.



Summary

Fortran has two great ways to write parallel code, but needs a third.

Shared-memory task parallelism is implemented in OpenMP, OpenACC, and in models associated with languages that aren't Fortran.

Task parallelism allows users to solve new types of problems and make better use of existing parallel features, especially DO CONCURRENT (e.g. when executing on GPUs).

Fortran tasks make new things possible and obviate the need for tedious and error prone implementations. They also reduce the need for non-standard extensions like OpenMP and OpenACC.

Please do not let whatever you don't like about my syntax to get in the way $oldsymbol{arphi}$



Questions/Comments

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See <u>https://github.com/ParRes/Kernels</u> p2p* for details...

Motivation for Asynchrony 3

```
#pragma omp parallel
#pragma omp master
for (int i=1; i<m; i+=mc) {</pre>
  for (int j=1; j<n; j+=nc) {</pre>
    #pragma omp task \
             depend(in:grid[i-mc][j],grid[i][j-nc]) \
             depend(out:grid[i][j])
    for (int ii=i; ii<std::min(m,i+mc); ii++) {</pre>
      for (int jj=j; jj<std::min(n,j+nc); jj++) {</pre>
        A[ii][jj] = A[ii-1][jj] + A[ii][jj-1] - A[ii-1][jj-1];
#pragma omp taskwait
                                This pattern appears in a range of applications:
```

• Dynamic programming for sequence alignment e.g. Smith-Waterman/PairHMM (bioinformatics)

• Deterministic neutron transport

• Linear algebra (e.g.NAS LU benchmark)



 $A_{i,i} = A_{i-1,i} + A_{i,i-1} - A_{i-1,i-1}$



